



Matrix Factorization & Latent Semantic Analysis Review

Yize Li, Lanbo Zhang



Overview

- SVD in Latent Semantic Indexing
- Non-negative Matrix Factorization
- Probabilistic Latent Semantic Indexing



Vector Space Model

- A document: a vector in term space
- Vector computation: TF / TFIDF
- Similarity measure: angular cosine between query and documents.

$$\cos \theta_i = \frac{q * d_i}{|q| * |d_i|}$$

- Document vectors make up a term-document matrix.



Example

- 9 documents
- Terms in bold are in the dictionary.

c1: *Human machine interface* for Lab ABC computer applications
c2: A survey of user opinion of *computer system response time*
c3: The *EPS user interface* management system
c4: *System* and *human system* engineering testing of *EPS*
c5: Relation of *user-perceived response time* to error measurement

m1: The generation of random, binary, unordered *trees*
m2: The intersection *graph* of paths in *trees*
m3: *Graph minors IV: Widths of trees* and well-quasi-ordering
m4: *Graph minors: A survey*



Weakness of VSM

- Noise in term-document matrix
 - Synonyms
 - E.g. “car” & “automobile”.
 - Decrease recall
 - Polysems
 - E.g. “saturn”.
 - Decrease precision



Latent Semantic Indexing (LSI)

- $A_{m \times n}$: term-document matrix
- Singular Value Decomposition (SVD)

$$\mathbf{A} = \mathbf{U}\mathbf{W}\mathbf{V}^T$$

- Latent Semantic Indexing (LSI)

$$\mathbf{A}_k = \mathbf{U}_k \mathbf{W}_k \mathbf{V}_k^T$$



What's really happening?

- Transformation of space
 - **Original: Term space**
 - Basis $B_1 = \{e_1, e_2, \dots, e_m\}$, m is the term number in dictionary.
 - **New: Latent semantic space**
 - Basis $B_2 = \{u_1, u_2, \dots, u_k\}$, k is the truncated dimension of document vector.



Thinking with LSI

- LSI aims to find
 - Meaning behind words
 - Topics in documents
- Difference between topics and words
 - Words – observable
 - Topics – latent
 - Topic space
 - Latent semantic space
 - Each basis vector u_i represents a topic



Evaluation of LSI

■ Strength

- Filter out noise(synonyms, polysems): dimension reduction considers only essential components of term-document matrix.
- Reduces storage

■ Weakness

- Interpretation impossible: mixed signs
- Orthogonal restriction on basis vector
- Good truncation point k is hard to determine.



Non-negative Matrix Factorization

- Unlike SVD, we do matrix factorization as

$$\mathbf{A}_k = \mathbf{W}_k \mathbf{H}_k, \quad \mathbf{W}_k, \mathbf{H}_k \geq \mathbf{0}$$

- Topic space
 - Dimension: k
 - Basis $\mathbf{b}_3 = \{w_1, w_2, \dots, w_k\}$

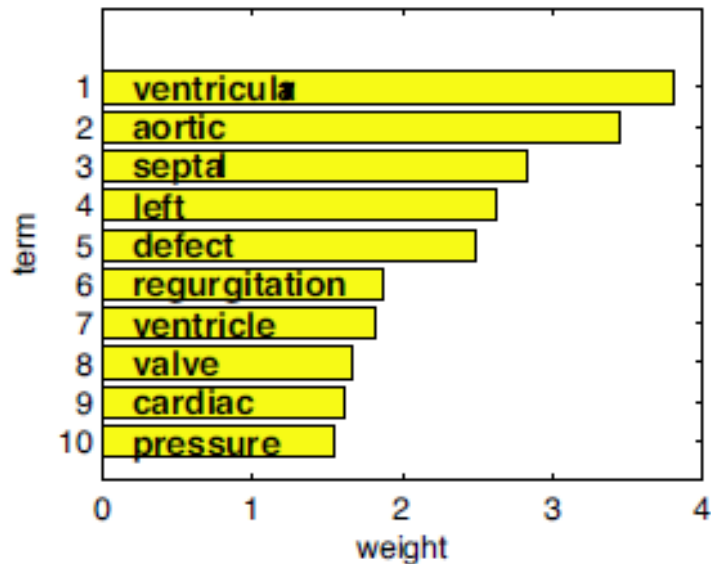


Properties of NMF

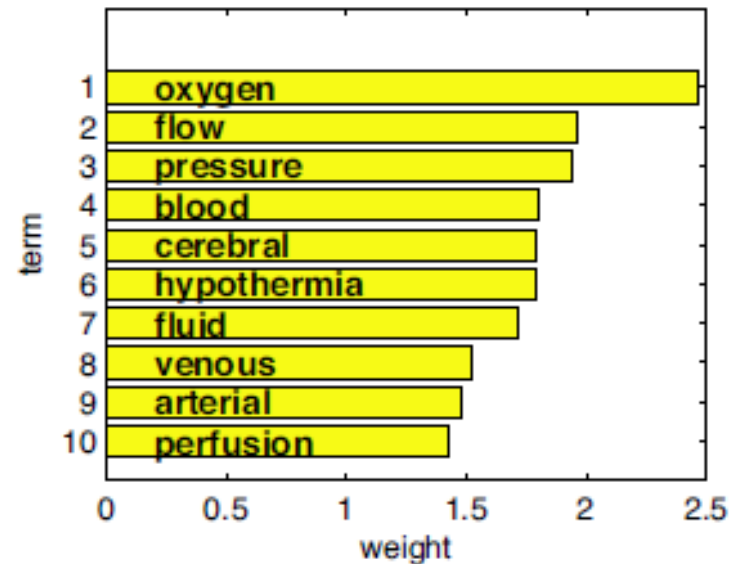
- No orthogonal restriction on basis vector
- Easy interpretation
 - Elements of W and H are all non-negative.
 - W_{ij} reflects how much basis vector w_j is related to term t_i
 - H_{ij} reflects how much document d_j points to the direction of basis vector w_i .



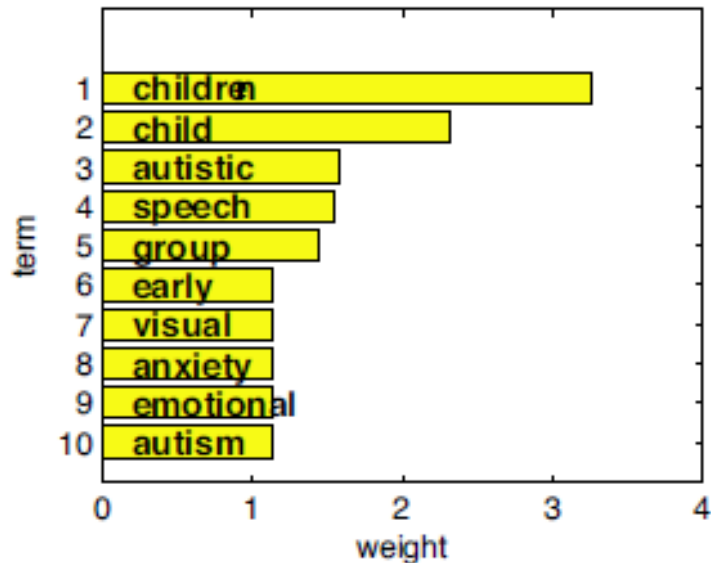
Highest Weighted Terms in Basis Vector W_1



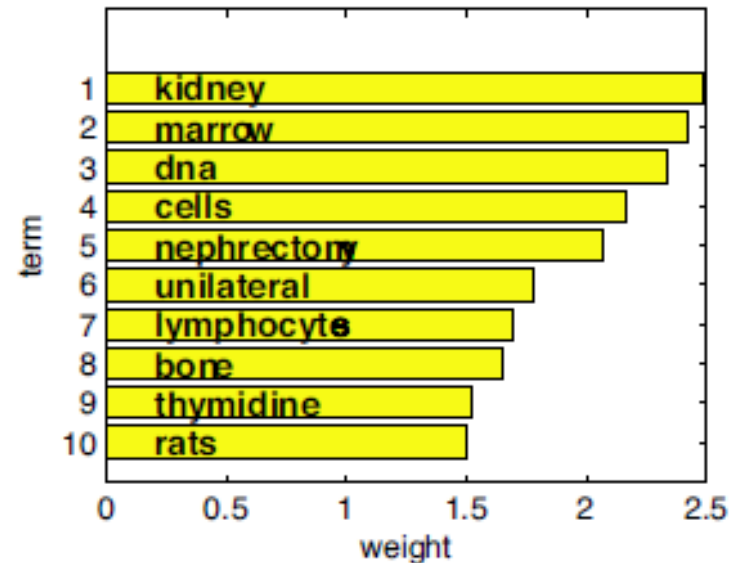
Highest Weighted Terms in Basis Vector W_2



Highest Weighted Terms in Basis Vector W_5



Highest Weighted Terms in Basis Vector W_6





Computation of NMF

$$[\mathbf{W}, \mathbf{H}] = \min \|\mathbf{A} - \mathbf{WH}\|_F^2, \text{ s.t. } \mathbf{W}, \mathbf{H} \geq \mathbf{0}$$

- Algorithms
 - Lee and Seung 2000
 - Berry etc. 2004

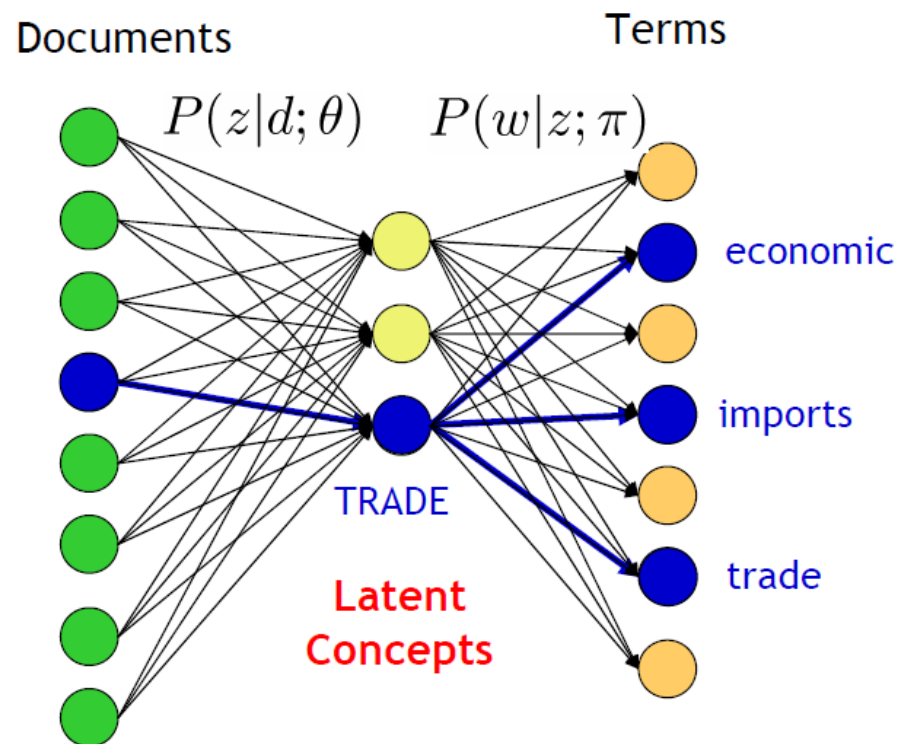


Evaluation of NMF

- Strength
 - Great interpretability
 - Improved Performance for document clustering comparing to LSI.
- Weakness
 - Factorization is not unique
 - Local minimum problem

pLSI: a probabilistic view of LSI

Why Latent Concepts?



Sparseness problem: terms not occurring in a document get zero probability

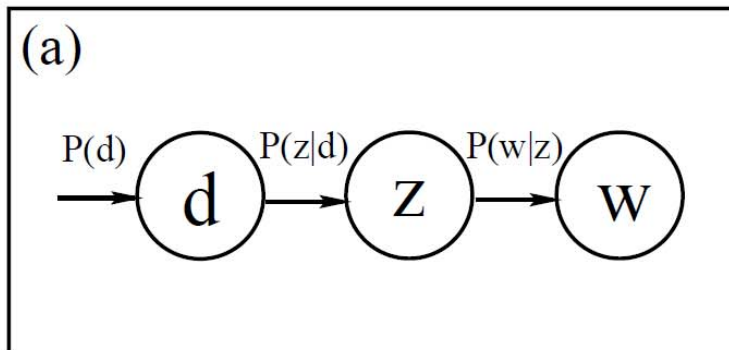
Concept expression probabilities are estimated based on all documents that are dealing with a concept

No prior knowledge about concepts required

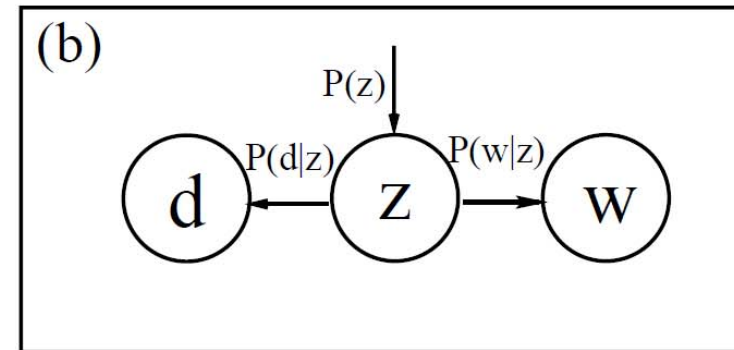
Dimension reduction

PLSA: Graphical model representation

$$\begin{aligned} P(d, w) &= P(d)P(w | d) = P(d) \sum_{z \in Z} P(w | z)P(z | d) \\ &= \sum_{z \in Z} P(d)P(w | z)P(z | d) \quad (a) \\ &= \sum_{z \in Z} P(d, z)P(w | z) \\ &= \sum_{z \in Z} P(z)P(w | z)P(d | z) \quad (b) \end{aligned}$$



Asymmetric decomposition



Symmetric decomposition



pLSA via Likelihood Maximization

- Log-Likelihood

$$L(D, W) = \prod_{d, w} \left(\sum_z P(w | z) P(z | d) \right)^{n(d, w)}$$

$$l = \sum_{d, w} n(d, w) \log \left(\sum_z P(w | z) P(z | d) \right)$$

- Goal : maximize the log-likelihood with the constraints

$$\sum_w p(w/z_l) = 1, \sum_z p(z/d_j) = 1$$



KL Projection

KL divergence is a measure of difference between the empirical data distribution and the model

$$l = \sum_{d,w} n(d,w) \log \left(\sum_z P(w|z)P(z|d) \right)$$
$$= \sum_d n(d) \left[\sum_w \frac{n(d,w)}{n(d)} \log P(w|d) + \log P(d) \right]$$

Recall KL divergence is $D_{\text{KL}}(P\|Q) = \sum_i P(i) \log \frac{P(i)}{Q(i)}$

$P = \hat{P}(w|d) = \frac{n(d,w)}{n(d)}$ $Q = P(w|d)$

Rewrite the underlined part: $-P \log \frac{1}{Q}$

PLSA via EM

- E-step: estimate posterior probabilities of latent variables, (“concepts”)

$$P(z | d, w) = \frac{P(d | z) P(w | z) P(z)}{\sum_{z'} P(d | z') P(w | z') P(z')} \quad \text{Probability that the occurrence of term } W \text{ in document } d \text{ can be “explained” by concept } Z$$

- M-step: parameter estimation based on expected statistics.

$$P(w | z) \propto \underbrace{\sum_d n(d, w) P(z | d, w)}_{\text{how often is term } W \text{ associated with concept } Z}$$

$$P(d | z) \propto \underbrace{\sum_w n(d, w) P(z | d, w)}_{\text{how often is document } d \text{ associated with concept } Z}$$

$$P(z) \propto \underbrace{\sum_{d, w} n(d, w) P(z | d, w)}_{\text{probability of concept } Z}$$

examples

	"segment 1"	"segment 2"	"matrix 1"	"matrix 2"	"line 1"	"line 2"	"power 1"	power 2"
10 most probable words in the respective latent classes (or factors)	imag SEGMENT texture color tissue brain slice cluster mri volume	speaker speech recogni signal train hmm source speakerind. SEGMENT sound	robust MATRIX eigenvalu uncertainti plane linear condition perturb root suffici	manufactur cell part MATRIX cellular famili design machinepart format group	constraint LINE match locat imag geometr impos segment fundament recogn	alpha redshift LINE galaxi quasar absorp high ssup densiti veloc	POWER spectrum omega mpc hsup larg redshift galaxi standard model	load memori vlsi POWER systolic input complex arrai present implement

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Most relevant latent classes for word "segment"

Most relevant latent classes for word "matrix"

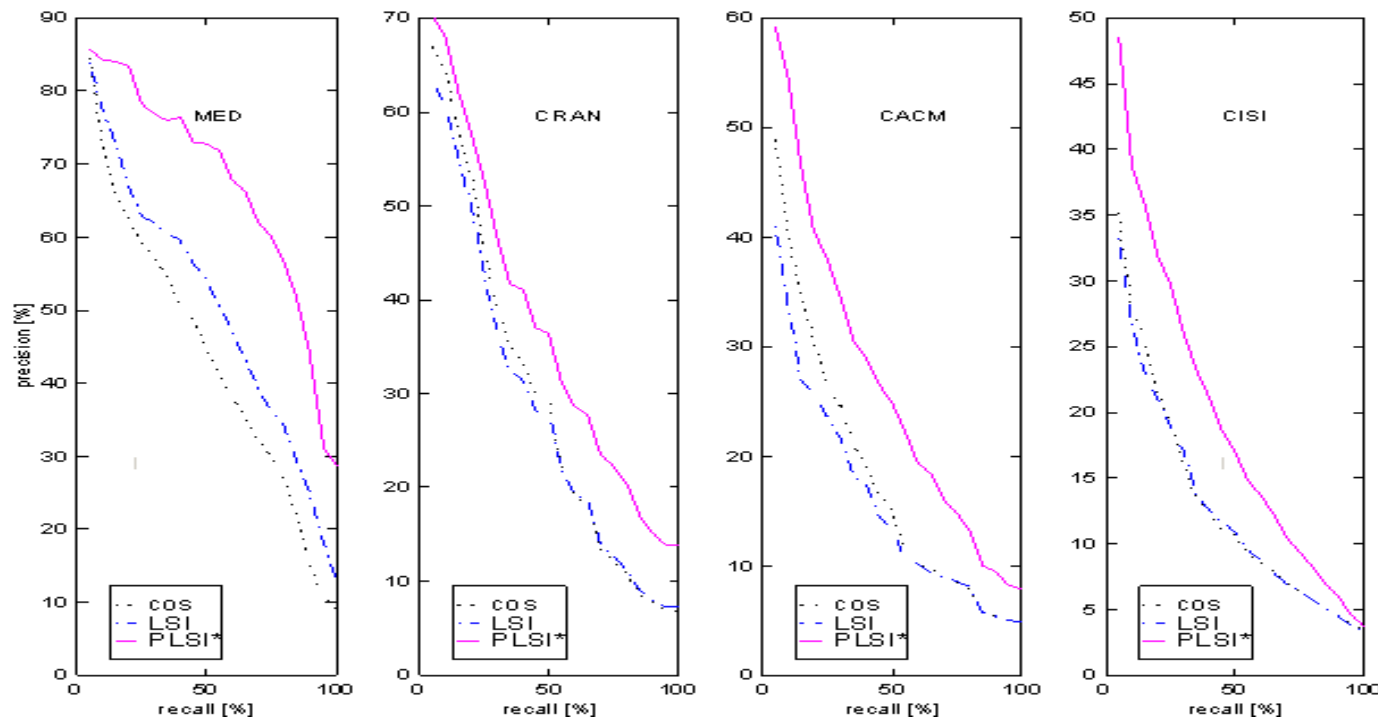
Most relevant latent classes for word "line"

Most relevant latent classes for word "power"

Model based on : 1568 documents on Clustering, Z=128

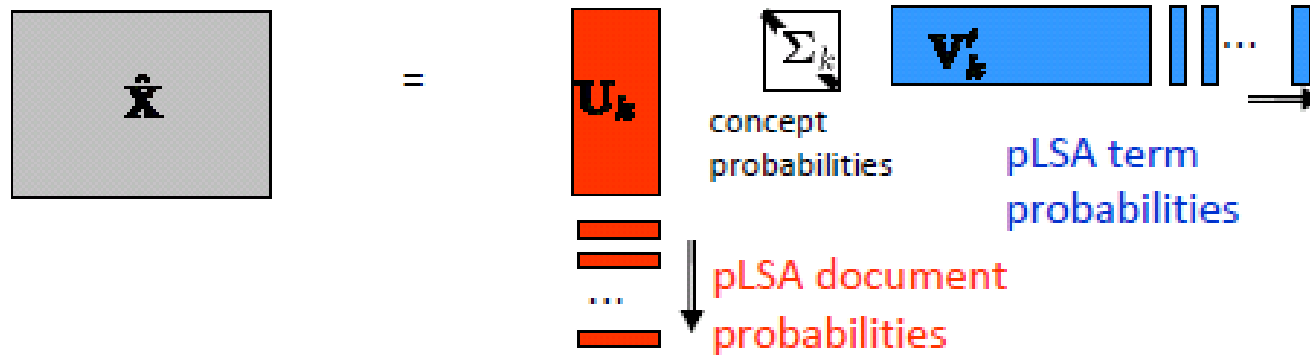
Performance comparison of a retrieval system: Three models, four document collection.

	MED		CRAN		CACM		CISI	
	prec.	impr.	prec.	impr.	prec.	impr.	prec.	impr.
cos+tf	44.3	-	29.9	-	17.9	-	12.7	-
LSI	51.7	+16.7	*28.7	-4.0	*16.0	-11.6	12.8	+0.8
PLSI	63.9	+44.2	35.1	+17.4	22.9	+27.9	18.8	+48.0



PLSA Mixture Decomposition vs. LSA/SVD

$$\hat{p}_{\text{PLSA}}(d, w) = \sum_z p(d|z) p(z) p(w|z)$$





PLSA vs. LSA

- Objective function: Frobenius norm vs. likelihood
- Non-negative
- Normalized
- There is no obvious interpretation of the directions in the LSA latent space; Multinomial word distribution in PLSA
- PLSA utilized statistical theory to determine the number of latent space dimension. LSA based on ad hoc heuristics



Relation between PLSA and NMF

- Any (local) maximum likelihood solution of PLSA is a solution of NMF with KL divergence
- KL divergence is a measure of the difference between the empirical distribution and the model
- Implications
 - Any problem which can be formulated with NMF, may be efficiently solved by PLSA



SVD in Collaborative Filtering

- Filling in missing values
 - Filling matrix using average value
 - EM algorithms

$$R = \begin{pmatrix} r_{11} & \cdots & r_{1M} \\ \vdots & \ddots & \vdots \\ r_{N1} & \cdots & r_{NM} \end{pmatrix} \approx \overbrace{\begin{pmatrix} w_{11} & \cdots & w_{1k} \\ \vdots & \ddots & \vdots \\ w_{N1} & \cdots & w_{Nk} \end{pmatrix}}^k \overbrace{\begin{pmatrix} v_{11} & \cdots & v_{1M} \\ \vdots & \ddots & \vdots \\ v_{k1} & \cdots & v_{NM} \end{pmatrix}}^M$$

Weighted -SVD

- Constant non-negative matrix $W \in \mathbb{R}_+^{n \times m}$.
- Weights the importance of each entry of the data matrix R

W						R					
0	1	1	1	1	0		1	1	0	2	
1	1	1	1	1	1	7	0	1	3	0	2
1	1	0	1	1	1	5	0		0	1	2
0	1	1	1	1	1		0	1	0	9	4

- Useful for masking missing entries of the matrix.
- Allows factorization to focus on certain pieces of the matrix.



NMF in Collaborative Filtering

- Objective: $Err(P, Q) = \sum_{(u,i) \in \mathcal{K}} (r_{ui} - p_u^T q_i)^2$
- Only deal with known values in R
- Can deal with large dataset



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EM for PCA/SVD:

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